

# I2C: Part1

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## I2C: part 1

### Introduction

In the previous Tutorial, we learned about **Interrupt**. In this tutorial we will learn about **I2C** communication.

### I2C Communication

**Inter-Integrated Circuit (I2C)**, is a two-wire communication protocol. This protocol is designed for **short-distance communication** between microcontrollers and peripherals. It uses two pins to set up the communication:

- **SDA**: Serial Data
- **SCL**: Serial Clock

This way of communication, allows us to connect more than 1 component to the same 2 pins. For **I2C** every component has its own address. These addresses are mostly **7-bit**.

**I2C** is a master and slave protocol. It means that one device (Our Arduino) is a **master**, and the other devices are **slaves**. A **master** device controls the **clock** created in **SCL**. Also, **master** decides that if it wants to communicate with a **slave** or not. Each message of **master** is like below:

Field	Bit Count	Bit Description
START	—	SDA goes LOW while SCL is HIGH → begins communication
Slave Address	7 bits	Unique address of target device (0–127)
R/W Bit	1 bit	0 = Write, 1 = Read
ACK/NACK	1 bit	Receiver pulls SDA LOW to acknowledge (ACK), HIGH for no-ack (NACK)

Field	Bit Count	Description
Data Byte	8 bits	First byte of data to write or read
1		
ACK/NACK	1 bit	Receiver acknowledges the byte
Data Byte	8 bits	Additional data bytes (optional, depends on protocol)
2...N		
ACK/NACK	1 bit	Acknowledge after each data byte
STOP	—	SDA goes HIGH while SCL is HIGH → ends communication

In the table above, you can see the message structure in **I2C**. First, **master** puts the **SDA** to low. This indicates that all **slaves** should listen. After that, it tells which **slave address** it wants to talk to. Then, with 1 bit tells the **slave** if it wants to read or write. Next, there would be an acknowledgement bit. If **slave** was available, it would set the acknowledgement bit to 0. (The default value of SDA is always 1). After that, there would be a byte of data. Respect to the mode (read or write), **master** can send or receive that byte. Then, whoever receives the data, should set the acknowledgement bit to 0. These byte transfer and acknowledgement can be repeated multiple times, until a stop signal. Stop signal can be created when we put the SDA to 1.

To have a **I2C** communication in **Arduino** uno, we should use these pins:

signal	pin
<b>SDA</b>	A4
<b>SCL</b>	A5

## Wire

To control the **I2C** communication, **Arduino** has a library called **Wire**. We can include **Wire** in our code like below:

```
#include <Wire.h>
```

To set up the **I2C** communication, we can use **.begin()** function, like below:

```
Wire.begin();
```

After doing that, we can start a communication with a **slave** in two ways:

- **write**
- **read**

To start a communication with a **slave** in order to **write**, we can use the code below:

```
Wire.beginTransmission(addr); // start the communication in
    ↵ order to write with the slave with the address of `addr`
Wire.write(data);           // write data
Wire.endTransmission();     // finish transmission
```

If we want to our communication to be a **read** communication, we can

```
Wire.requestFrom(addr, number); // start a read communication
    ↳ with the slave with the address of `addr` and read `number`-
    ↳ bytes
Wire.read();                      // read bytes
```

Let's connect an **I2C** component to the **Arduino** and check these functions.

## Finding I2C address

- Connect the clock
- write the code
- Explain the code
- end transmission = 0

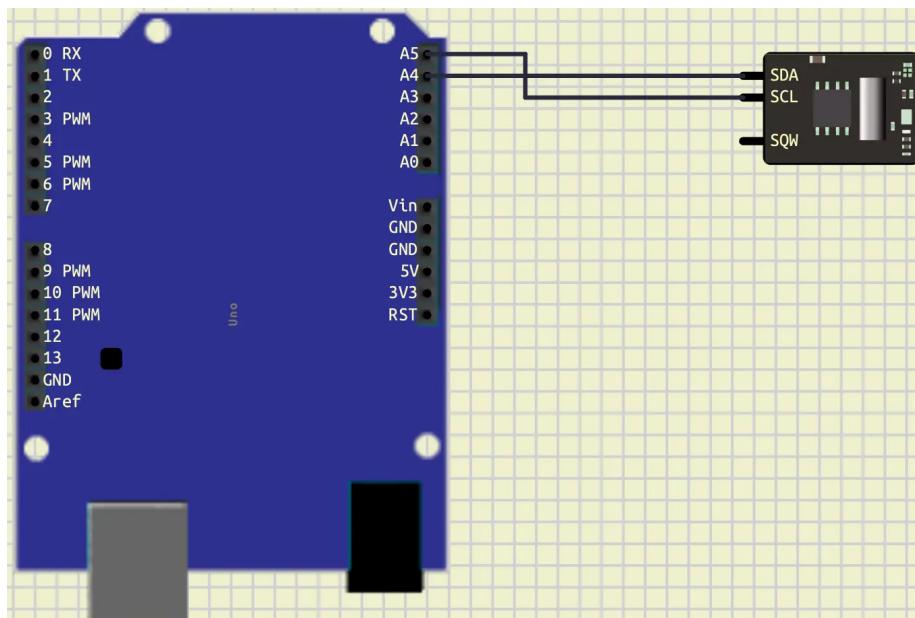


Figure 1: add-clock

```
#include <Arduino.h>
#include <Wire.h>
```

```

void setup()
{
    Wire.begin();
    Serial.begin(9600);
}

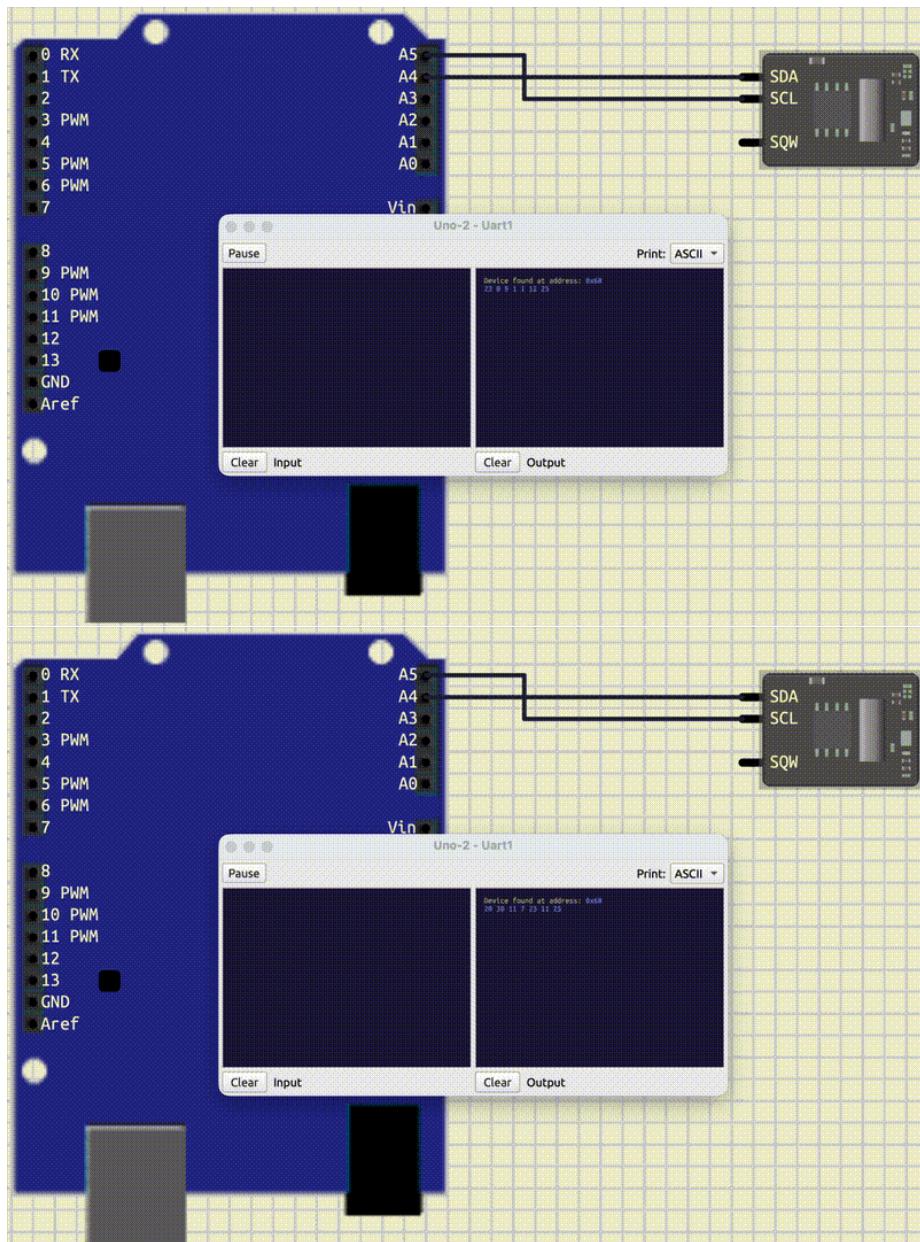
void loop()
{
    for (int i = 0; i < 127; i++)
    {
        Wire.beginTransmission(i);
        if (Wire.endTransmission() == 0)
        {
            Serial.println("Device found at address: 0x" + String(i,
← HEX));
        }
    }
    delay(2000);
}

```

## Clock: DS1307

- Storing: 0x22 -> 22 not 2\*16+2
- seconds, minutes, hours, weekday, day, month, year
- SQW: Square Wave Output
  - Good for creating interrupts

Register	Address
Seconds	0x00
Minutes	0x01
Hours	0x02
Day of Week	0x03
Day of Month	0x04
Month	0x05
Year	0x06



[Link to the Datasheet](#)

## OLED: SSD1306

```
lib_deps =  
    Adafruit SSD1306
```

### Adafruit GFX Library

```
#include <Adafruit_GFX.h>
#include <Adafruit_SSD1306.h>

#define SCREEN_WIDTH 128
#define SCREEN_HEIGHT 64

Adafruit_SSD1306 display(SCREEN_WIDTH, SCREEN_HEIGHT, &Wire);

if (!display.begin(SSD1306_SWITCHCAPVCC, SSD1306_ADDRESS))
{
    Serial.println("SSD1306 failed!");
    for (;;)
        ;
}

display.setTextSize(1);
display.setTextColor(WHITE, BLACK);

display.clearDisplay();
display.setCursor(0, 0);

display.print();
display.display();
```

Good Example

**Project**

**Conclusion**

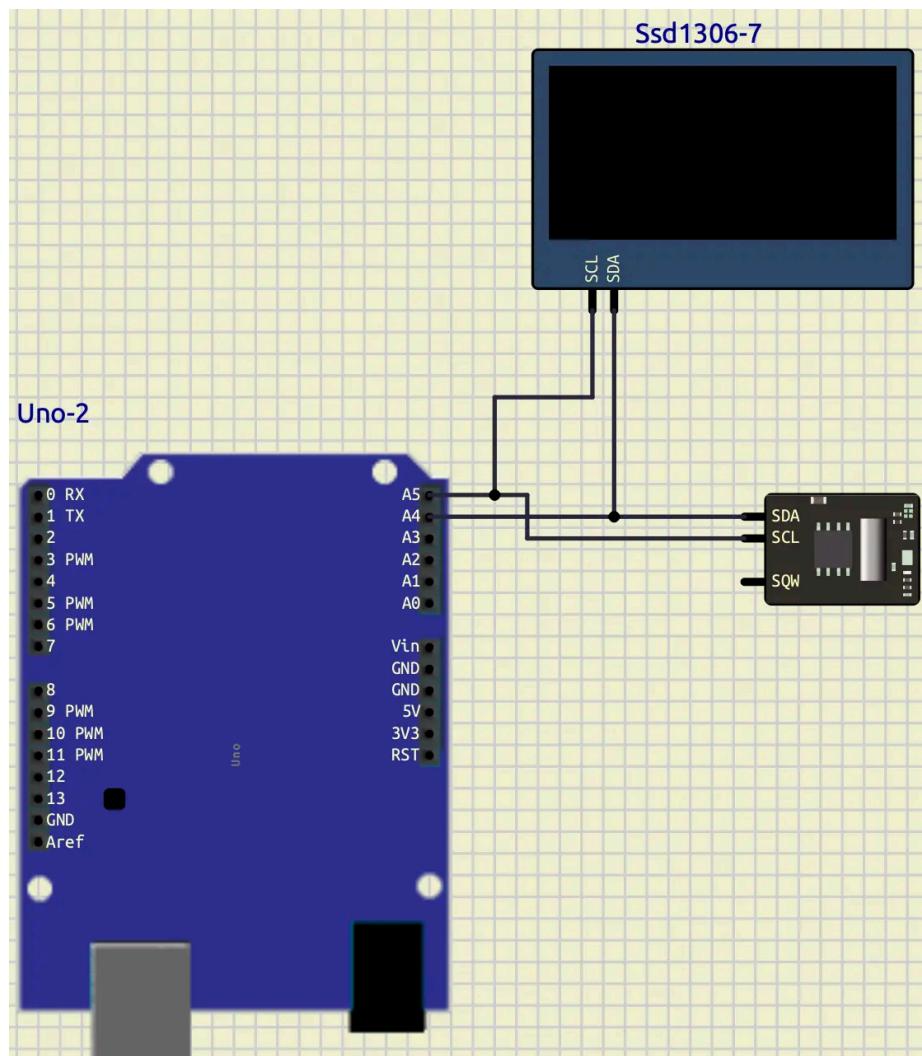


Figure 2: OLED

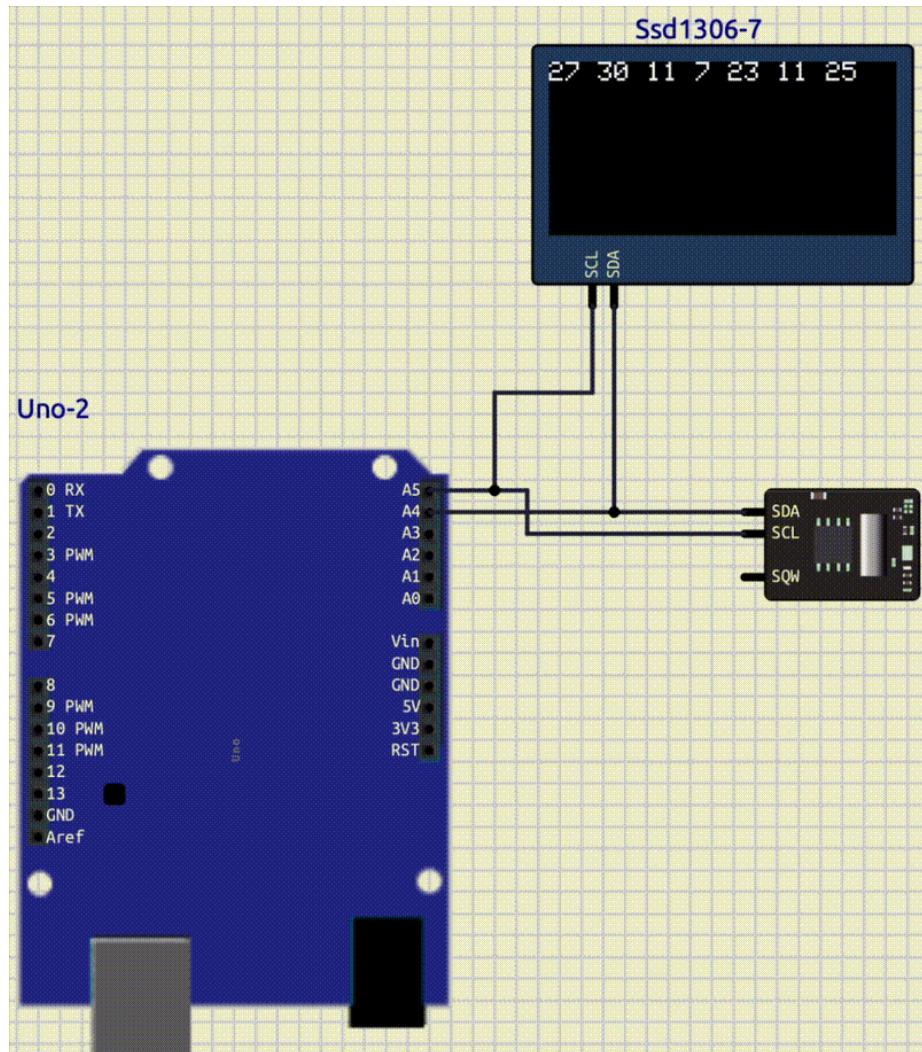


Figure 3: OLED gif

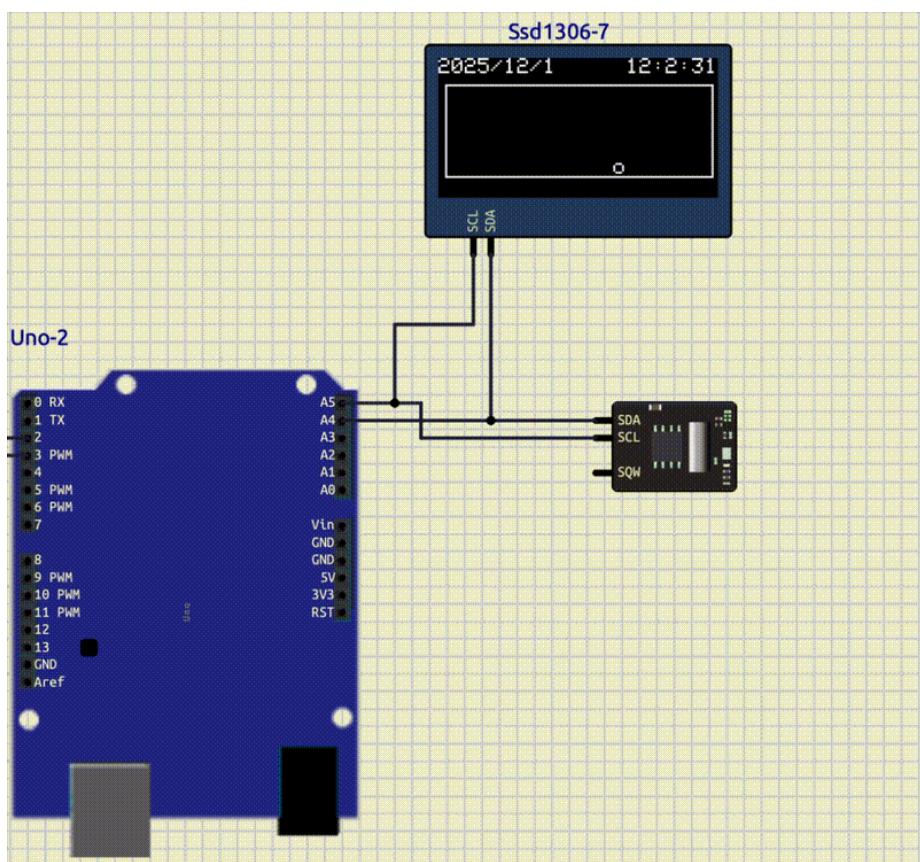


Figure 4: oled ball

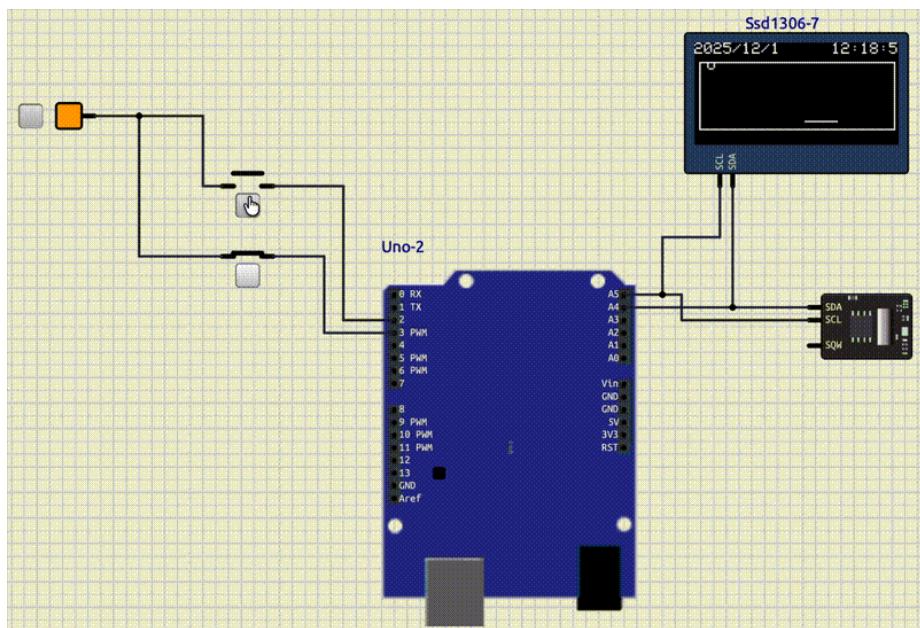


Figure 5: OLED Ball line